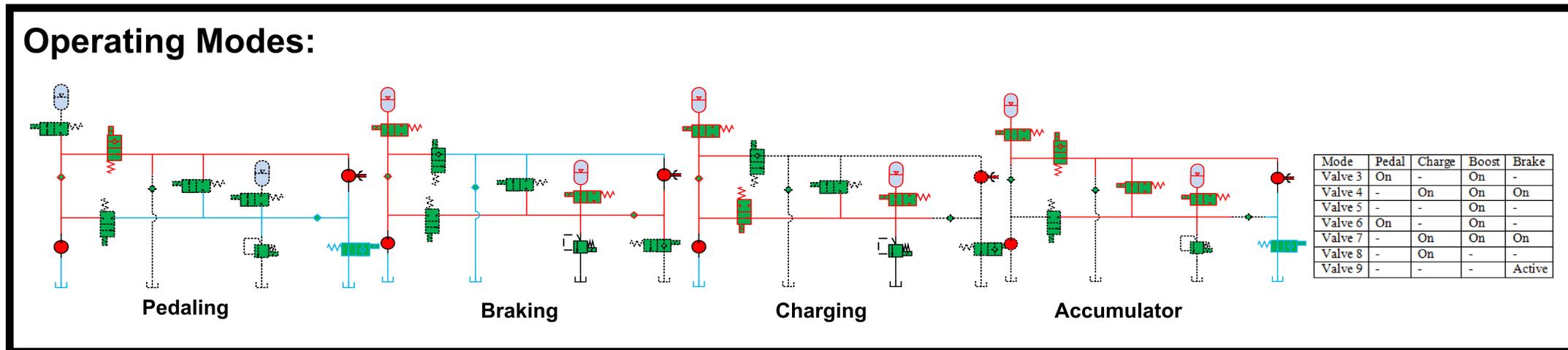
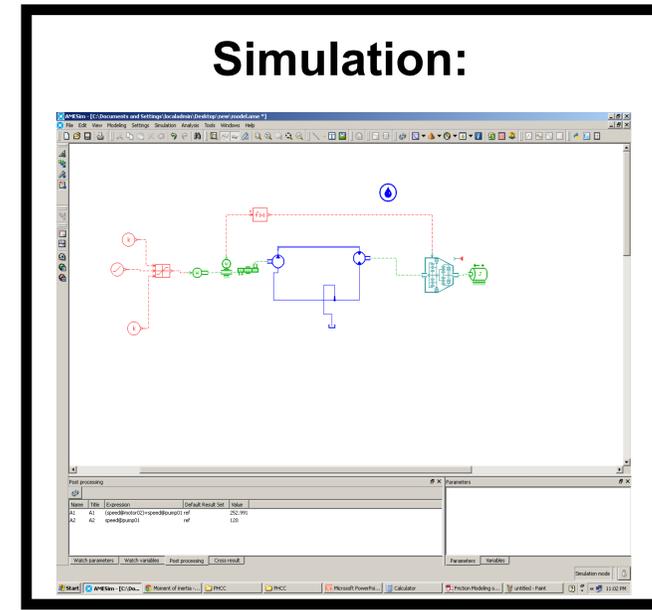
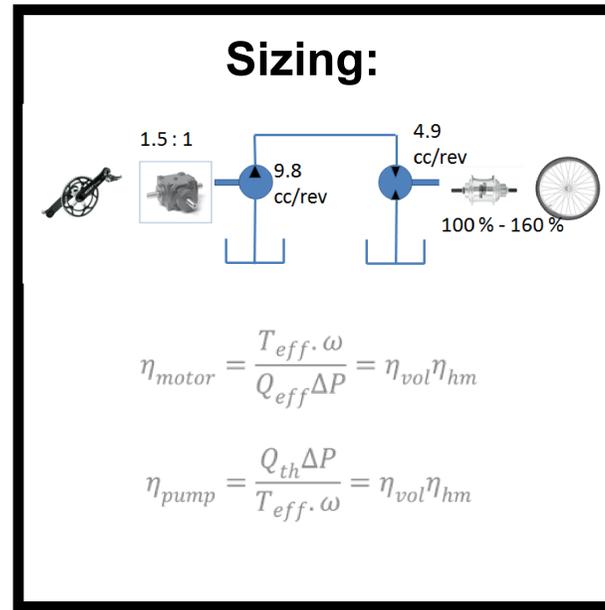
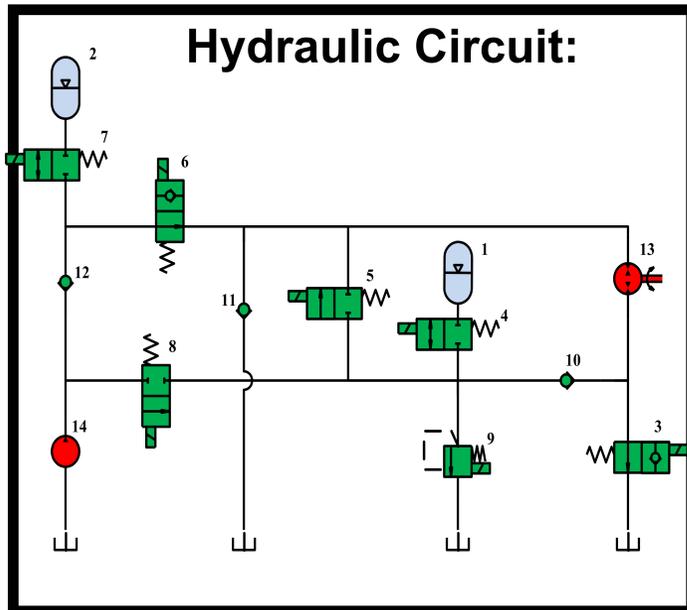
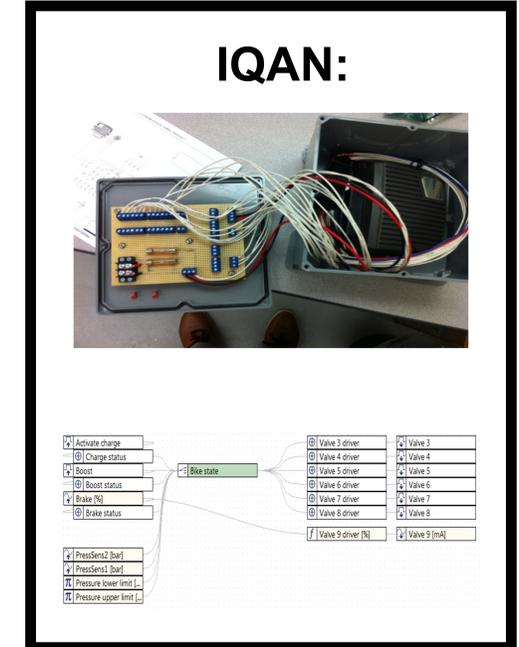


Jonathan Geske (ABE – Machine Systems), John Lamneck (ABE – Machine Systems), Mitchell Sparenberg (ASM), Kyle Ezra (ME), Birendra Kujur (ME), Hao Zhu (ME), Under Supervision of Professor Andrea Vacca Parker Contact: Bruce Larkin

Concept:

The purpose of this project was to create a hydraulic or pneumatic driven bicycle that is powered by human input. The team decided to chose a hydraulic drive vehicle due to the fact that there can be more force delivered with hydraulic oil than air. The basic concept of the vehicle was a two wheeled bicycle powered by a hydrostatic transmission. A gearbox is turned using the riders legs/feet, this powers a pump that drives fluid to a motor. The motor is connected to an internal gear hub on the rear wheel. There are four modes of the hydraulic circuit; Pedaling, Braking, Charging, and Accumulator. These are all directed by cartridge valves put into a valve block. Parker Hannifin's IQAN software was used to program the controller.



Parts/Cost:

COMPONENT	DESCRIPTION	PRICING (\$)
Pump/motor	Axial piston	615
Pump	Axial piston	700
Accumulator 1	B Series Piston Accumulator	400
Accumulator 2	B Series Piston Accumulator	309
6 Directional Valves	Bi-Directional Electrohydraulic valves Poppet Type, 2-Way	500 (estimated)
Proportional relief Valve	Poppet Type, 2-Way Valve	400 (estimated)
2 Check Valves	Valve, Hydraulic Check	100 (estimated)
Hydraulic Fluid	Mobile Hydraulic Fluid – 5gal	200 (estimated)
Electronic components	for control box assembly	120
Hoses and Fitting		350
Bicycle Frame		200
Additional bicycle parts	Seat, rear wheel, sprockets etc. Internal gear hub, speed reducer, and oil	865
Batteries and charger		190
Control Unit	IQAN-MC2	
Tools	Bicycle tools	20
Materials cost	Frame materials	300
Labor Cost		7200
	TOTAL	12,469